

# **Global Exploration Workshop**

## **– Moon Mission Concept with Re-usable Lunar lander**

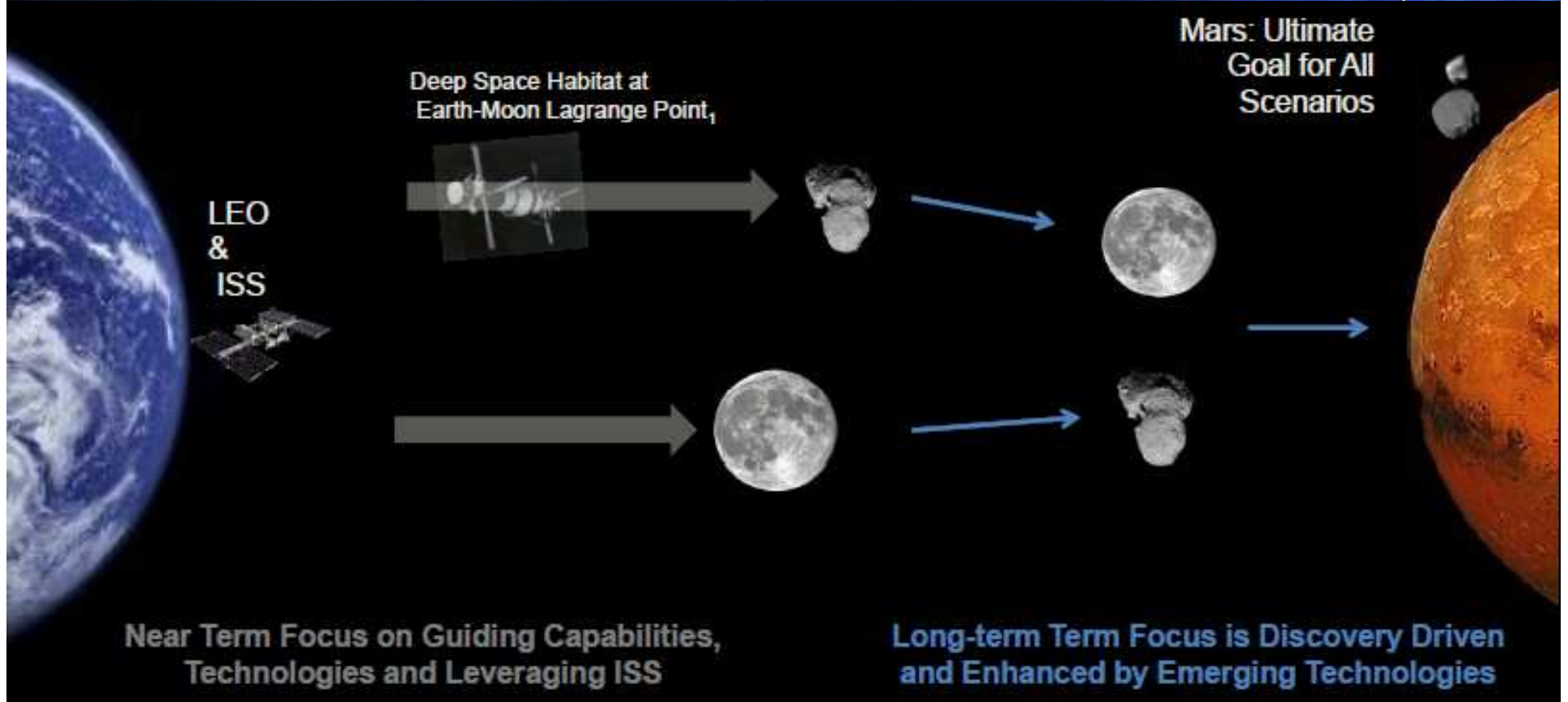
**Ben Donahue**  
Sr. Principle Engineer, Phantom Works

November 15, 2011

# Global Exploration Roadmap

Defense, Space & Security  
**Space Exploration**

International Space Station

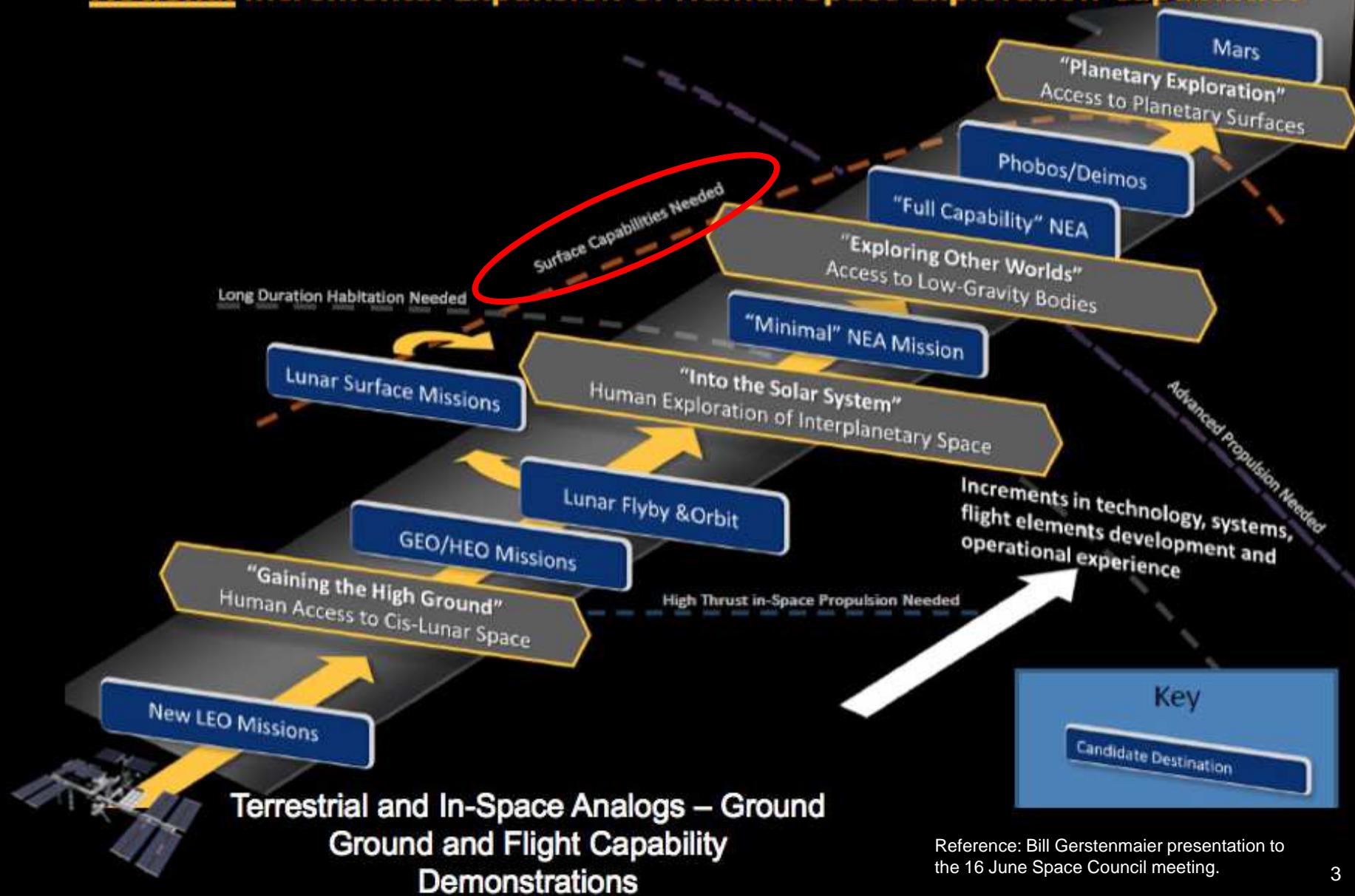




# Capability Driven Exploration



## Notional Incremental Expansion of Human Space Exploration Capabilities

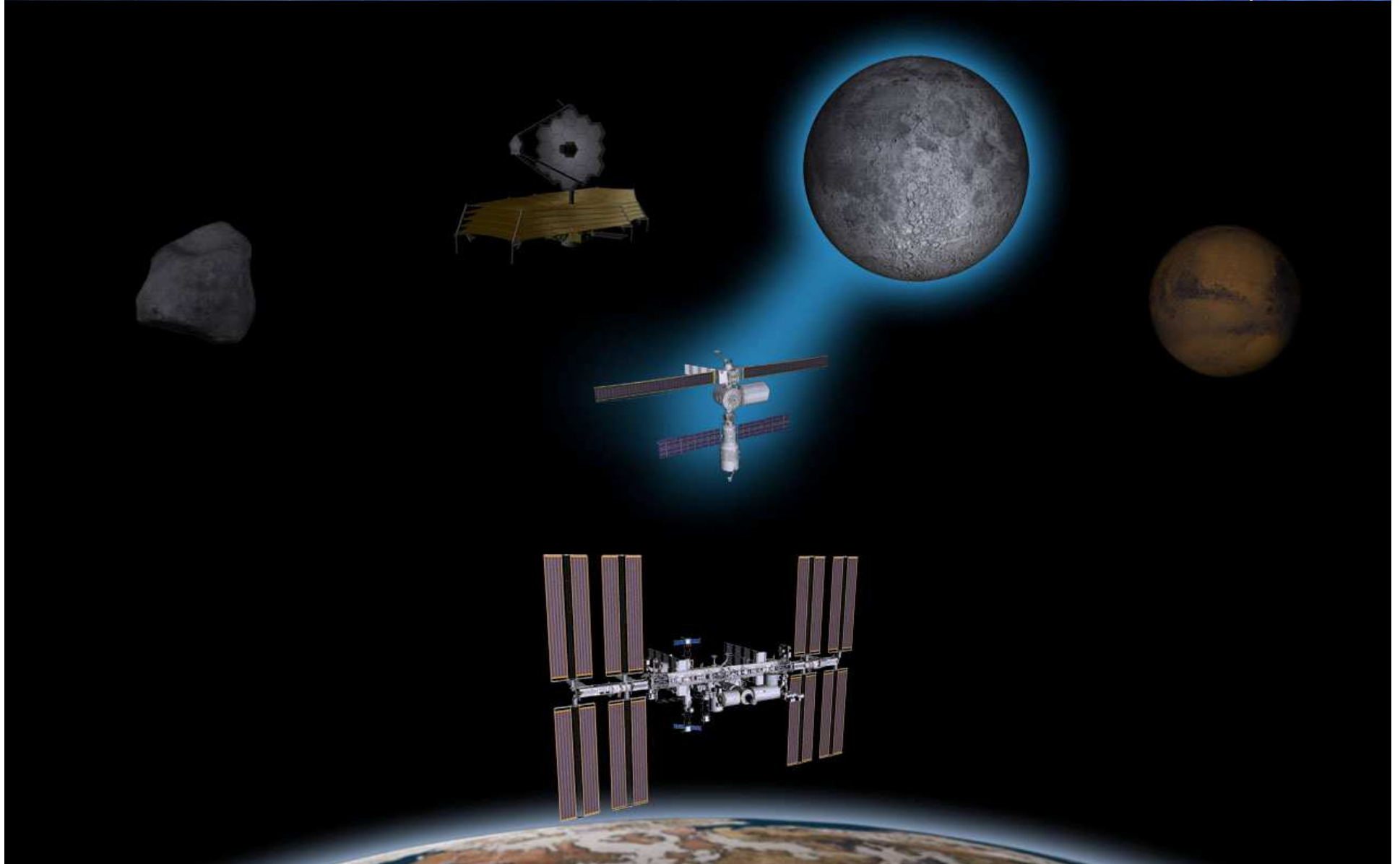


Reference: Bill Gerstenmaier presentation to the 16 June Space Council meeting.

# Flexible Path for Exploration

Defense, Space & Security  
**Space Exploration**

International Space Station



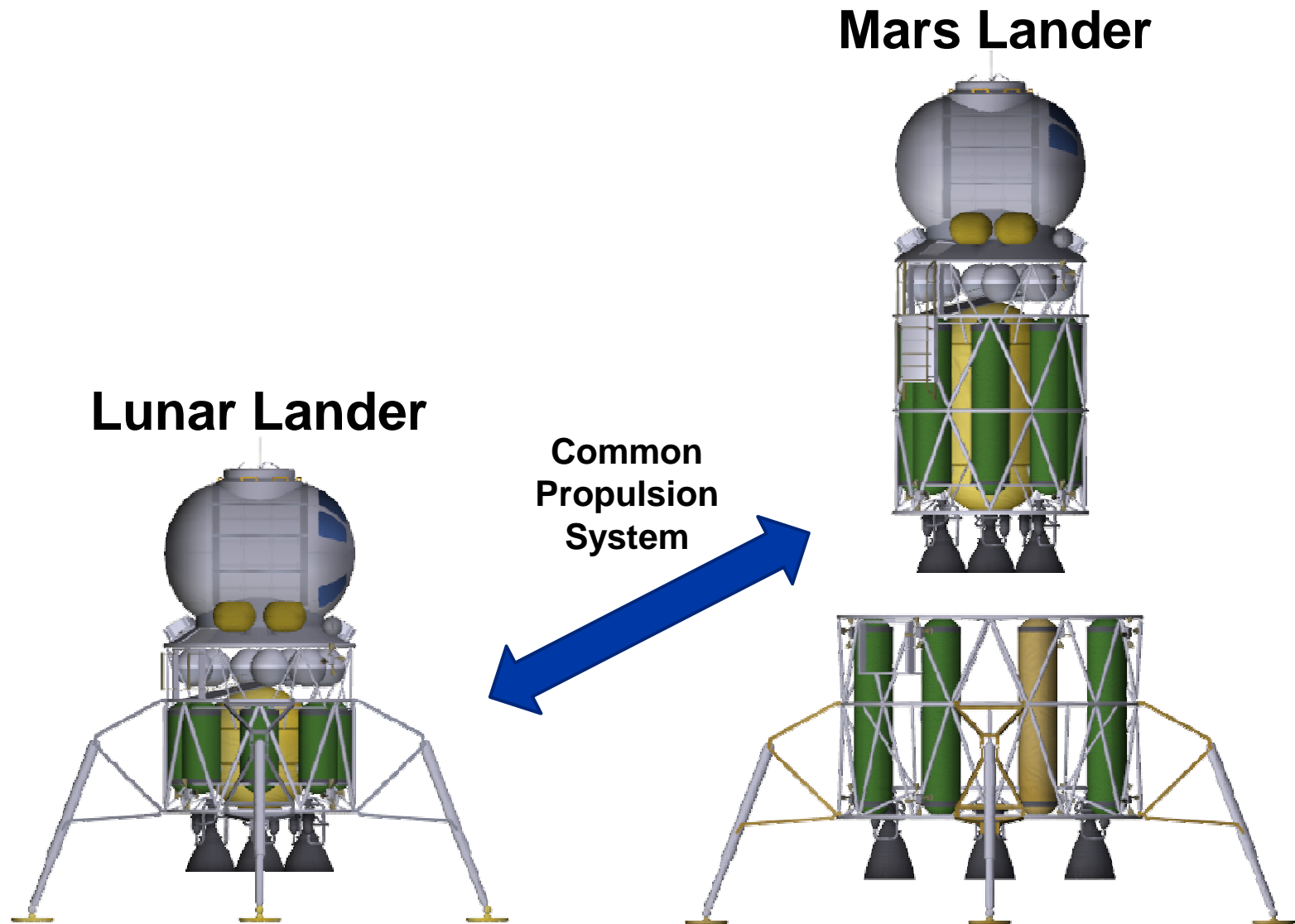
# Re-usable Lunar Lander Based at EML1 / 2

- A Gateway at EML1 or EML2 allows re-usability of the lunar lander which saves money and enhances development of the ultra-reliable systems needed for Mars
- Our concept lander is much smaller than Altair; Dry mass of 7t, wet mass of 15t (Altair was ~45t wet)
- The propulsion system is designed to be re-fuelable LOX/Methane





# Lunar Lander as a Pathfinder for Mars

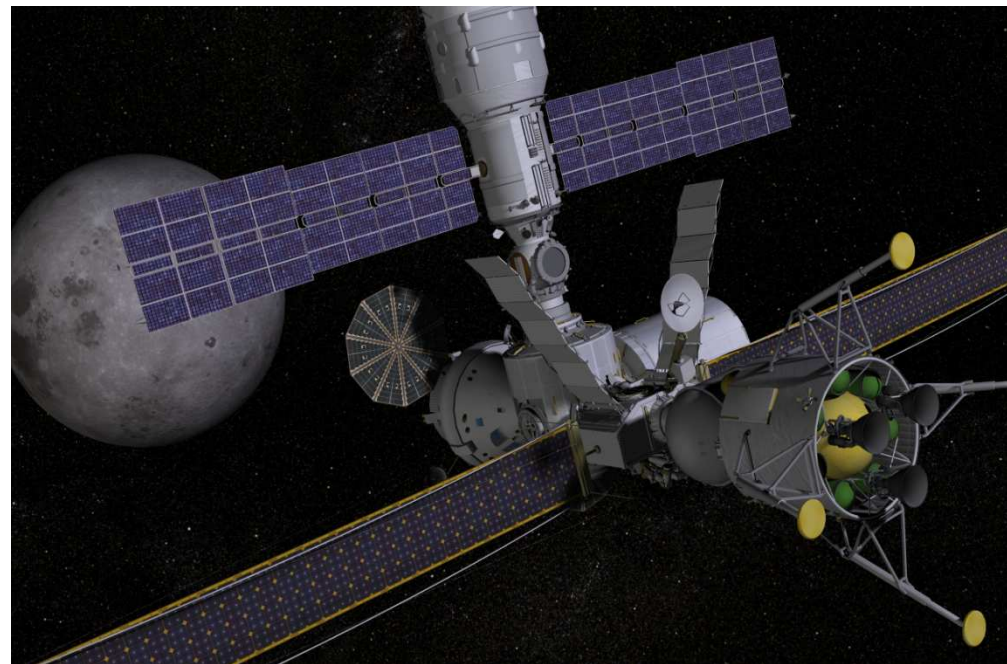


# Delivery of the Lunar Lander to the ISS-EP

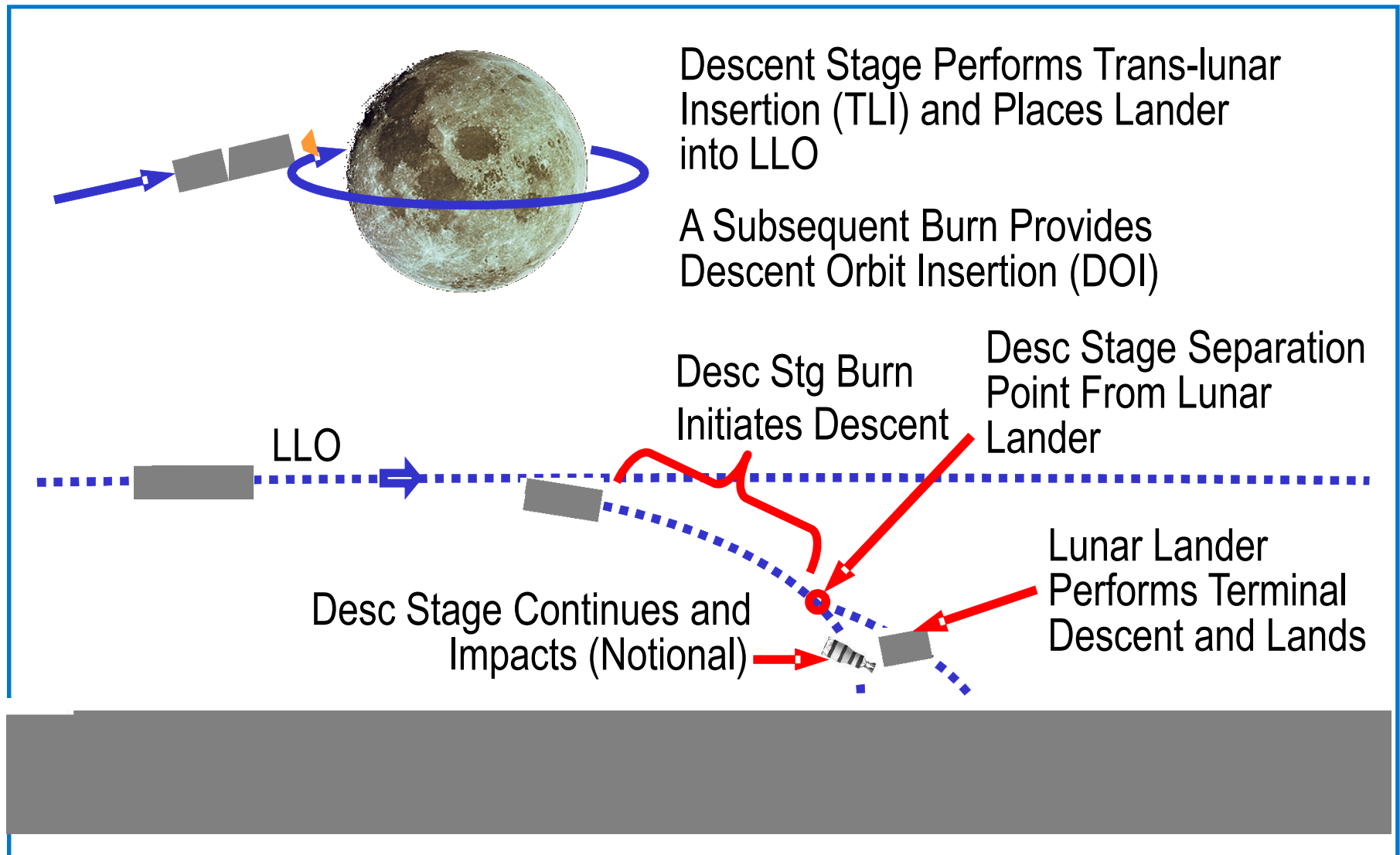
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International Space Station



- **Commissioning crew flies with the lander to the platform**
- **Flight test program in the vicinity of the ISS-EP is used to prepare the lander for it's first landing**



# Lunar Mission Flight Profile

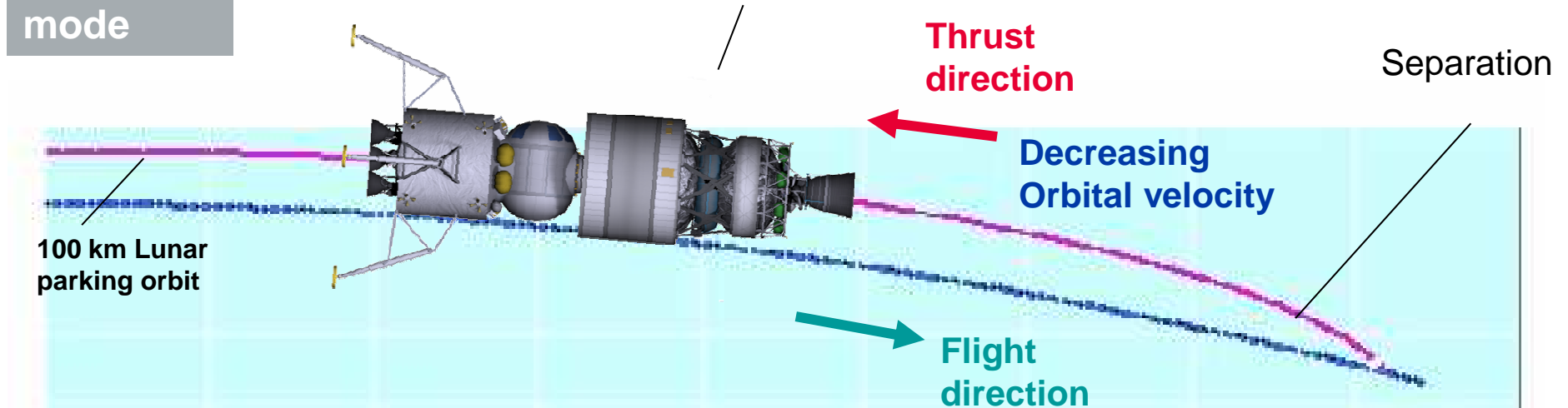




# Lunar Mission Flight Profile

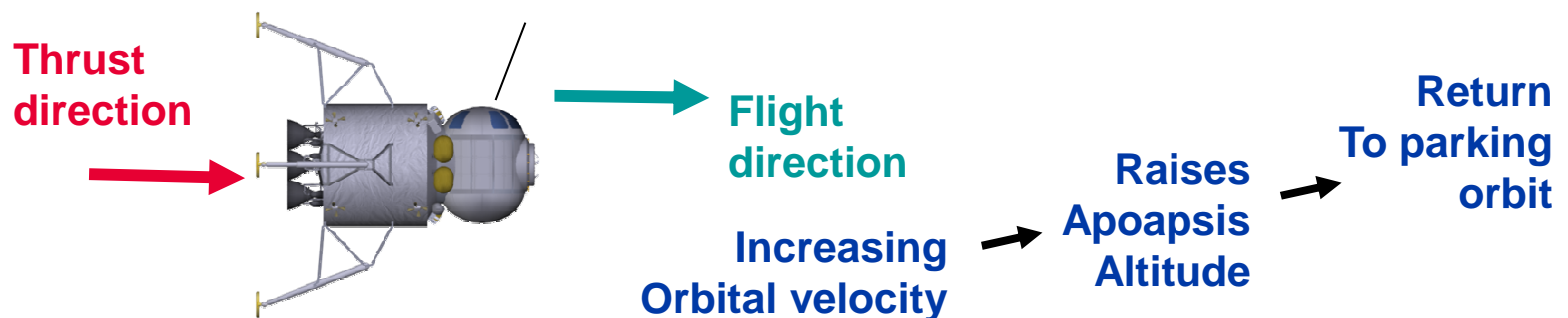
## Nominal mode

### Nominal Descent Profile Vehicle Attitude



## Abort mode

### "Abort the Descent" Profile Vehicle Attitude

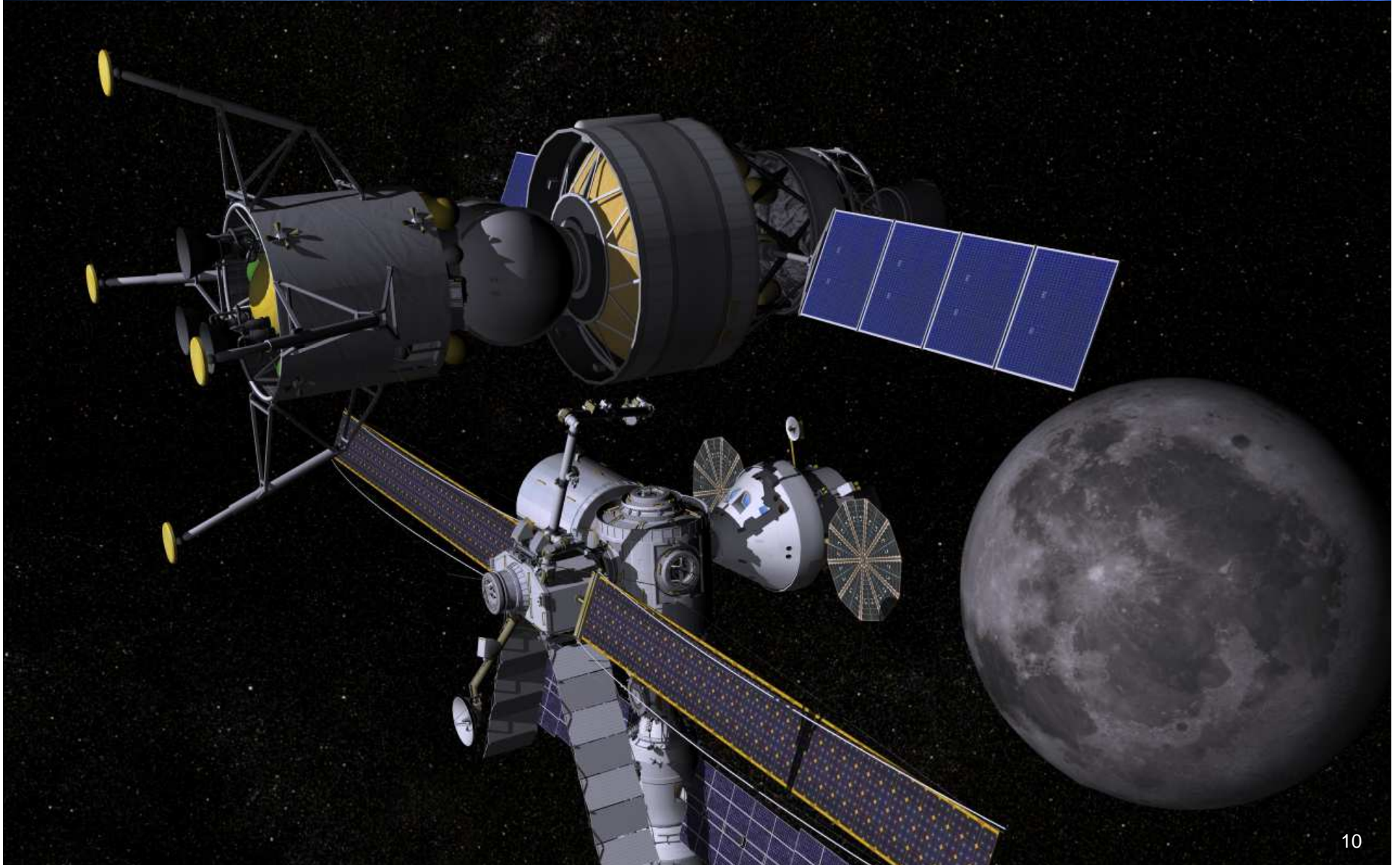


**No Lander rotation required to initiate Abort to orbit burn  
Lander is already in position to fire engines to return to orbit**

# Lunar Lander Departing the ISS-EP

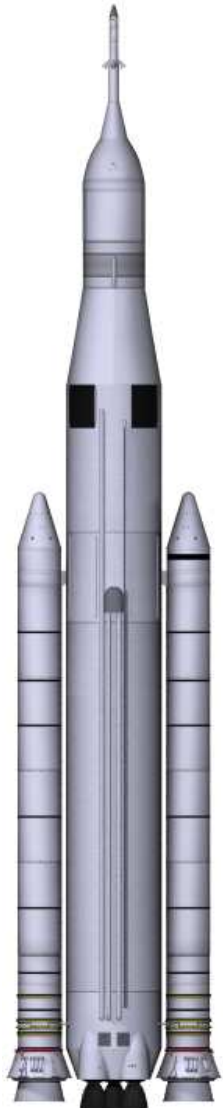
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# Initial SLS Capability

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- SLS provides the initial launch capability for exploration missions
- Lunar Mission Study Challenge:
  - Fly a complete lunar mission cycle with a single SLS launch





# Third Stage Evolution

Delta 5m Upper Stage



ARES 5.5m Tooling used to build demonstration tank

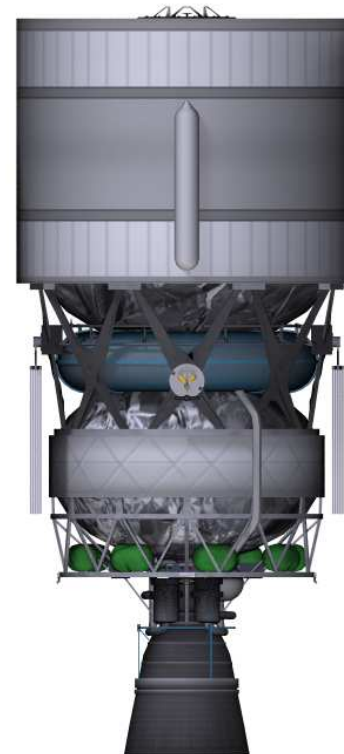
## Block 1



- Tank increase from 5m to 5.5m
- 27t to 40t Capacity

## Block 2a

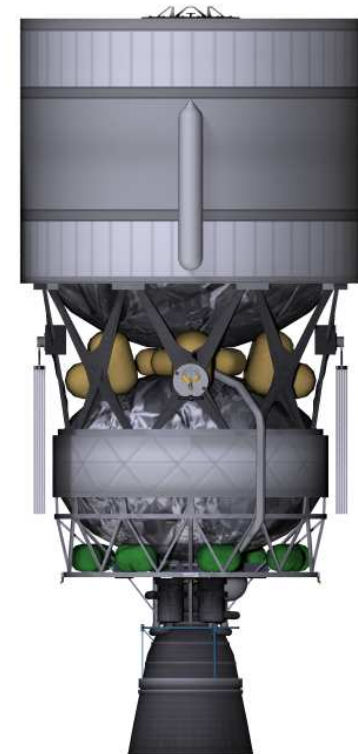
“Moon First”



- Block 2 NDS
- Orbit Kit
- Methane Tank

## Block 2b

“NEA First”



- Block 2 NDS
- Orbit Kit
- RL-10 Throttle

# Block 2a Third Stage for SLS

## ■ **Block 2a:**

- “Moon First” Configuration
- Adds solar array system
- AR&D functionality
- Enhanced RCS capability
- NDS with fluid transfer capability
- Additional tank (toroidal) for lunar lander methane delivery
- **Assumes SLS 2<sup>nd</sup> stage will be completed**



# Lunar Lander Recurring Operations



- The goal for recurring operations should be to deliver the crew and all fuel for the lander in a single SLS launch



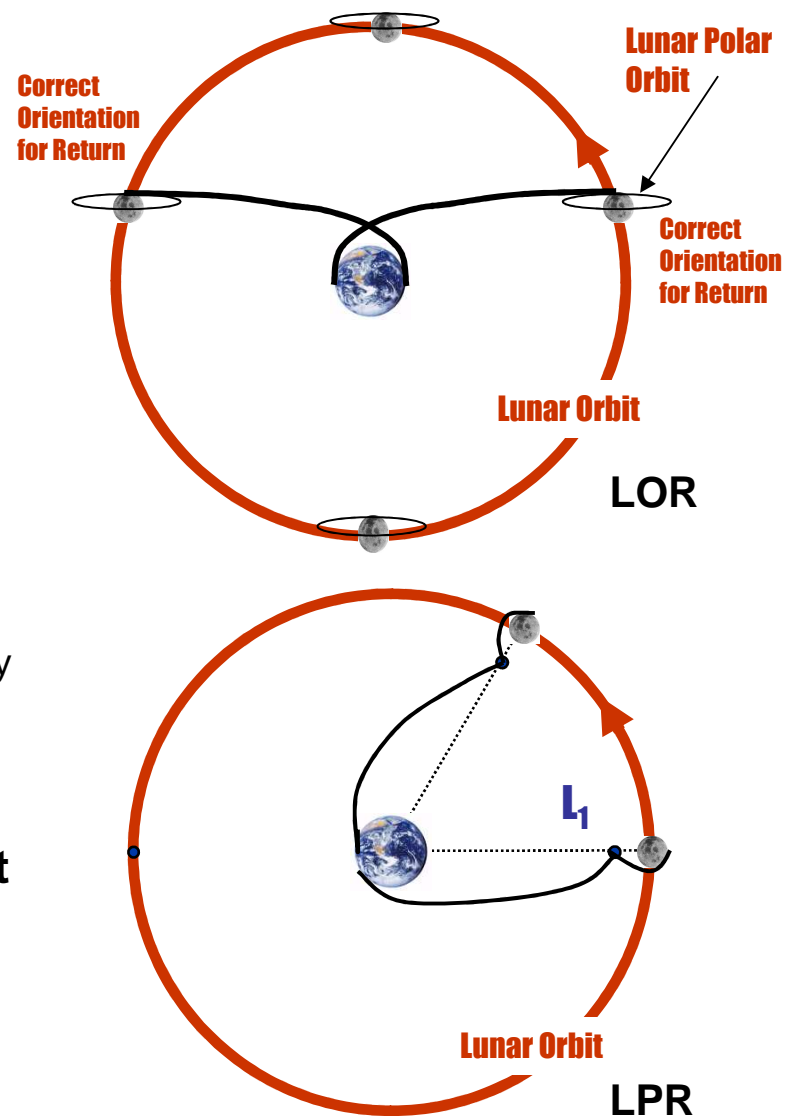
- The SLS third stage acts as the descent stage for the lander and performs the lunar orbit injection burn as well as most of the lunar descent burn
- This allows for the most efficient use of propellant because the high energy LOX/LH third stage is used immediately after it gets to L1 and long term storage of liquid hydrogen is not required
- The expensive crew cabin and ascent stage are re-used for multiple missions saving \$\$ Billions



# Lunar Site Access

## ■ Operational Considerations

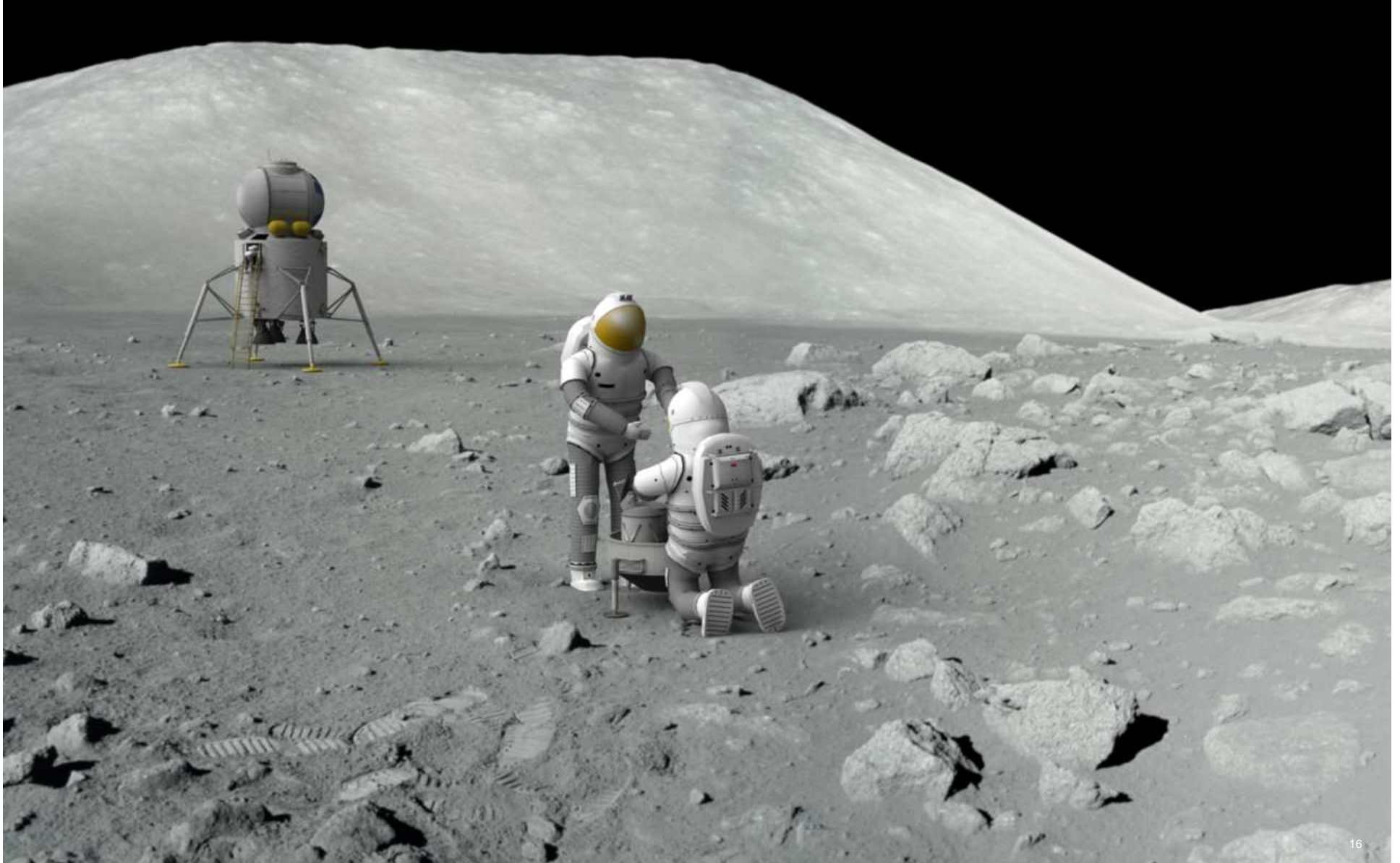
- Lunar Orbit Rendezvous (LOR)
  - Access to lunar poles would require polar orbit if LOR mission mode utilized
  - Lunar polar orbit provides infrequent opportunities for trans-Earth injection (once every 14 days)
- Orbit orientation inertially fixed, aligns with efficient trans-Earth trajectory twice a month
  - Total  $\Delta V = 8951$  m/s
- Libration Point Rendezvous (LPR)
  - Continuous access from  $L_1$  to lunar surface and return
  - Lunar rotation and libration point motion naturally synchronized
    - Continuous access to Earth - landing point partially controllable
    - Total  $\Delta V = 10480$  m/s
- Unique science opportunities at  $L_1$
- Deep-space human exploration analogs exist at  $L_1$
- Support for deep-space human exploration missions



# Lunar Lander on the Surface

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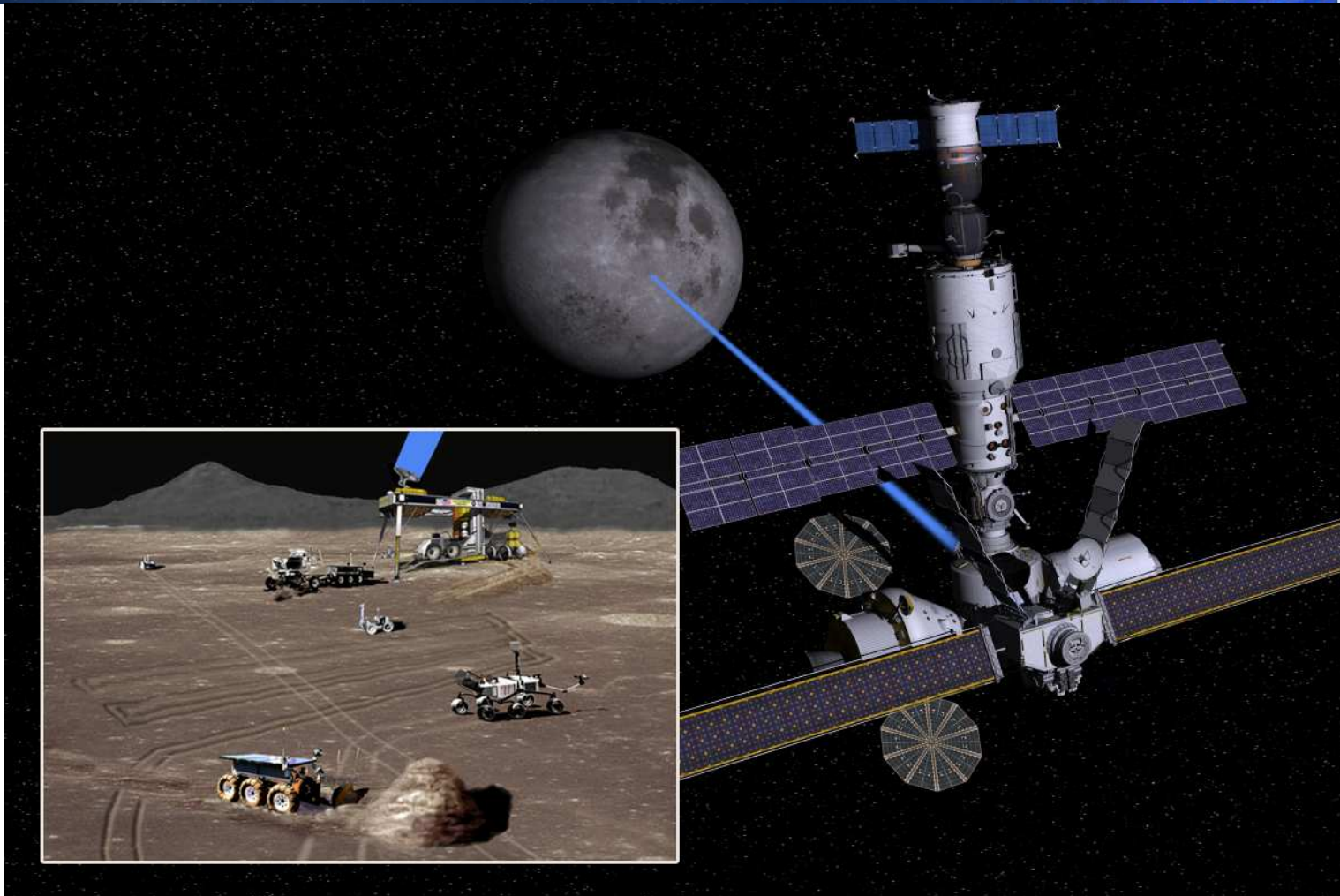




# Telepresence Precursor

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International Space Station



On-orbit telerobotic control is a new way of viewing human-robot cooperation.

**Dan Lester, Research Fellow**  
**Department of Astronomy**  
**[dfl@astro.as.utexas.edu](mailto:dfl@astro.as.utexas.edu)**

**University of Texas at Austin 512-471-3442**



# Lunar Mission – Summary



- **Re-usable Lander – Pathfinder for Mars**
- **“Global Access” from EML1/2**
- **Telerobotics Precursor Potential**



# Backup Charts

# Lunar Surface Reusable Surface Hab and Crew Lander

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# Crew Lander –15 mt Total Mass

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	mass	delta-V
<b>Total Systems Mass</b>	<b><u>14.98 mt</u></b>	
<b>Surface Payloads</b>	<b><u>0.50 mt</u></b>	
<b>Total Lander Mass</b>	<b><u>14.48 mt</u></b>	
<b>Crew Cabin and Systems</b>	<b><u>3.15 mt</u></b>	
<b>Dry Mass</b>	<b><u>2.72 mt</u></b>	
<b>Propellant total</b>	<b><u>8.61 mt</u></b>	
<b>Propellant Masses</b>	<b><u>8.61 mt</u></b>	<b><u>3,133 m/s</u></b>
<b>Propel Reserves</b>	<b><u>0.17 mt</u></b>	
<b>L1 to LLO Prop Main</b>	<b>n / a</b>	
<b>L1 to LLO RCS</b>	<b>0.02 mt</b>	<b>5 m/s</b>
<b>Terminal Desc Propel Main</b>	<b>1.92 mt</b>	<b>500 m/s</b>
<b>Terminal Desc RCS</b>	<b>0.04 mt</b>	<b>10 m/s</b>
<b>Ascent Propel Main</b>	<b>5.20 mt</b>	<b>1950 m/s</b>
<b>Ascent RCS</b>	<b>0.04 mt</b>	<b>10 m/s</b>
<b>LLO to L1 Prop Main</b>	<b>1.18 mt</b>	<b>640 m/s</b>
<b>L1 RCS Prop</b>	<b>0.04 mt</b>	<b>18 m/s</b>

# Lunar Mission Mass Estimates

**Table 4. Lunar Crew Sortie Mission Mass (mt)**

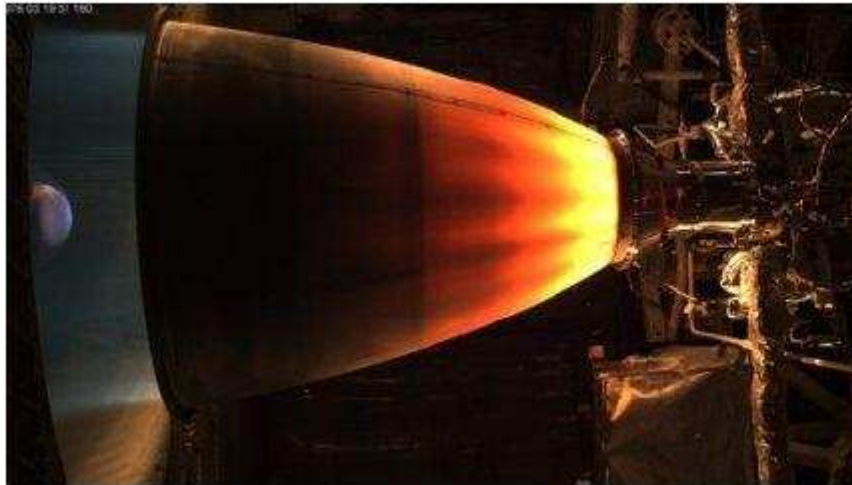
	Location	Mass	2 <sup>ND</sup> Stg	3 <sup>RD</sup> Stg	MPCV	L1 Payl	Lander	adapt	Comment	prop used
1	Asc L1 (2Stg)	209.6	138.3	45.0	16.7	6.7	n / a	2.9	29tg burn1	121.6
2	Asc L1 (3Stg)	69.0	n / a	45.0	16.7	6.7	n / a	0.6	39tg burn1	24.9
3	EML1	44.1	n / a	20.4	16.7	6.7	n / a	0.6	arrive L1	n / a
4	EML1	44.1	n / a	20.1	16.7	6.7	n / a	0.6	3Stg connect	n / a
5	Sep from L1	35.6	n / a	20.1	n / a	n / a	14.9	0.6	add lander	n / a
6	Depart L1	35.6	n / a	20.1	n / a	n / a	14.9	0.6	39tg burn2	5.0
7	LLO	30.6	n / a	15.1	n / a	n / a	14.9	0.6	arrive LLO	n / a
7	LLO-desc	30.6	n / a	15.1	n / a	n / a	14.9	0.6	39tg burn3	9.5
8	desc	21.1	n / a	5.6	n / a	n / a	14.9	0.6	3Stg jettison	n / a
9	Desc lander	14.9	n / a	n / a	n / a	n / a	14.9	n / a	lander desc	2.0
10	On L Surf	12.9	n / a	n / a	n / a	n / a	12.9*	n / a	lander asc	5.3
11	LLO	7.5	n / a	n / a	n / a	n / a	7.5	n / a	lander to L1	1.2
12	EML1	6.3	n / a	n / a	n / a	n / a	6.3	n / a	arrive L1	n / a
13	Depart L1	16.7	n / a	n / a	16.7	n / a	n / a	n / a	MPCV sep from L1	

\* 0.5mt Surface payload drop

# LO2 / Methane CH4 Engines for Descent and Ascent



**ISRU derived Methane may be used for Mars ascent descent**  
**Developmental programs underway at Aerojet and ATK/COR**  
**LO2 residuals left in desc stg tanks available Crew on surface**  
**Pump-fed Methane engine provides significant Isp (372 sec)**  
**over press-fed storable engine (320-328)**  
**Shared propel tank O2/CH4 main / RCS system in test**



Aerojet, T = 5.5 k-lbf, Isp = 350 sec



ATK/XCOR, T = 7.5 k-lbf



# Lander Close Up View

Legs in  
stowed  
position

Legs  
deployed

